

Winter 2022

Updated October 30, 2021

AERO 470 Control of Aerospace Vehicles [Bernstein] – TTh 9:00-10:30

AEROSP 548 [Kolmanovsky] Astrodynamics – MW 4:30-6:00

AERO 550 (EECS 560) (ME 564) (CEE 571) Linear System Theory
[Freudenberg] - MWF 9:30-10:30

AERO 551 (EECS 562) Nonlinear Systems and Control [Meerkov] – MW
1:30-3:00

AERO 552 Aerospace Information Systems [Jeannin] – TTh 1:30-3:00

AERO 580 (EECS 565) Linear Feedback Control [Seiler] - TTh 10:30-
12:00

AERO 740 Multi-agent systems [Panagou] – TTh 10:30-12:00

EECS 419 Electric Machines and Drives [Hofmann] – TTh 3:00-4:30

EECS 460 Control Systems Analysis and Design [Ozay] – MW 10:30-
12:00

EECS 461 Embedded Control [Cook] – TTh 9:00-10:30

EECS 464 (ROB 464) Hands-on Robotics [Revzen] – TTh 10:30-11:30

EECS 467 Autonomous Robotics [TBD] – MW 9:00-10:30

EECS 508 Control and Modeling of Power Electronics [Avestruz] – MW
10:30-12:00

EECS 536 Power Markets [Mathieu] – TTh 9-10:30

EECS 560 (AERO 550) (ME 564) (CEE 571) Linear System Theory
[Freudenberg] – MWF 9:30-10:30

EECS 561 (ME 561) Design of Digital Control systems [Vasudevan] –
TTh 10:30-12:00

EECS 562 (AERO 551) Nonlinear Systems and Control [Meerkov] - TTh
1:30-3:00

EECS 565 (AERO 580) Linear Feedback Control [Seiler] - TTh 10:30-
12:00

EECS 567 (ROB 510) (ME 567): Robot Kinematics and Dynamics [Gregg]
– MW 10:30-12:00

EECS 568 (ROB 530) (NA 568) Mobile Robotics [Ghaffari] – MW 5:00-
7:00

EECS 569 Production Systems Engineering [Meerkov] - TTh 4:30-6:00

EECS 598-006 Motion Planning [Berenson] – MW 3:00-4:30

EECS 598-002 Reinforcement Learning Theory [Ying] – TThu 10:30-12:00

ME 542 (AUTO 542) Vehicle Dynamics and Automation [Orosz] - TTh 1:30-3:00

ME 548 Applied Nonlinear Dynamics [Epureanu]-MF 4:30-6:00

ME 561 (EECS 561) Design of Digital Control systems [Vasudevan] - TTh 10:30-12:00

ME 564 560 (AERO 550) (EECS 560) (CEE 571) Linear System Theory [Freudenberg] - MWF 9:30-10:30

ME 565 Battery Systems and Control [Siegel] – MW 12:00-1:30

ME 567 (ROB 510) (EECS 567): Robot Kinematics and Dynamics [Gregg] – MW 10:30-12:00

ME 599 (CEE 501) (ROB 599) (ISD 599) Dynamics and Control of Connected Vehicles [Orosz] - TTh 12:00-1:30

NA 483 Marine Control Systems [Amini] -- TTh 1:30-3:00

NA 568 (ROB 530) (EECS 568) Mobile Robotics [Ghaffari] – MW 5:00-7:00

NA 599-065 Marine Robotics (Skinner) – TTh 9:00-10:30

ROB 464 (EECS 464) Hands-on Robotics [Revzen] – TTh 10:30-11:30

ROB 510 (ME 567) (EECS 567): Robot Kinematics and Dynamics [Gregg] – MW 10:30-12:00

ROB 520 Motion Planning [Berenson] – MW 3:00-4:30

ROB 530 (EECS 568) (NA 568) Mobile Robotics [Ghaffari] – MW 5:00-7:00

ROB 550 Robotics Systems Laboratory [Gaskell]

Interesting IOE courses

IOE 510 Linear Programming I [Epelman] – MW 9:00-10:30

IOE 511 Continuous Optimization Methods [Berahas] – TTh 9:00-10:30

IOE 614 Integer Programming [Lee] – MW 12:00-1:30